# ohammad Mahdi Rahimi

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#### Research Interests

Theory Artificial Intelligence, Reinforcement Learning, Game Theory, Ethics and Sociology

**Practice** Robotics, Multi-Agent Systems, Big-Data and Distributed Processing, Web and Information retrieval

### Research Experience \_\_\_\_\_

**Research Assistant** Sep. 2020 - Sep. 2025

MOON LAB - EE DEPARTMENT @ KAIST

Prof. JeaKyun Moon

- Exploring role of Memory Augmentation on Deep Learning
- Focusing of Multi-Agent Reinforcement Learning methods and Distributed/Federated learning.

**Research Assistant** Dec. 2017 - Dec. 2019

COGNITIVE ROBOTICS LAB - CS DEPARTMENT @ AMIRKABIR UNIVERSITY OF TECHNOLOGY

Prof. Saeed Shiry Gheydari

- Implementation of AI and Control algorithms for 2D Soccer Simulation.
- Implementation of Vision and Control for Rescue Simulation on Gazebo and ROS.

Research Assistant Feb 2015 - Feb 2019

PARSIAN ROBOTICS LAB - EE DEPARTMENT @ AMIRKABIR UNIVERSITY OF TECHNOLOGY

Prof. Mohammad Azam Kosravi

- Implementation of the AI and the Optimization algorithms for real-time vision-guided multi-agent soccer robotic, extbfROBOCUP SSL.
- Implementation of a **Reinforcement Learning** for kick-off plan positioning.
- Implementation of a user-friendly Graphical Plan Designer and Plan Execution Engine that anyone can design a strategy without any code.
- More than 2 years of **Leadership Experience** in a team larger than 20 members.
- Developer and Maintainer of Grsim the official open-source simulator of Robocup-SSL (+21 contributors, +68 forks).
- Re-basing the Robocup SSL base code from monolithic to a multi-agent distributed architecture on ROS framework.

**High School Research** Sep. 2011 - Sep. 2014

EMJA ROBOTICS LAB - EMAMJAVAD HIGH SCHOOL

- A team of two omni-directional autonomous soccer robots.
- · Work with Atmega16 micro-controller and XBee, Gyroscope and Ultra-Sonic distance meter modules.
- Filtering IR sensors on 38khz.
- Implement Two-way communication and collaboration between two soccer robots.
- Implement PID-Controller to fix robot direction and DC-Motor velocity control.

## Work Experience \_

**Data Engineer** 1-Year Dec. 2019 - Dec. 2020

MCI TELECOMMUNICATIONS (THE LARGEST TELECOM COMPANY IN MIDDLE-EAST)

• Work on Hadoop Ecosystem and tools like Hive, Yarn

- Work with distributed queues Zookeeper, Kafka and Avro
- Work with Elasticsearch, Logstash, Kibana and Beats for collecting data specially logs and metrics
- · Analyse and process data with Spark and Flink
- · Visualise the result with Grafana
- · distributed deployment and configuration management with Redhat Ansible
- Core R&D member for Bigdata solutions in MCI
- Individually developed and deployed the first distributed full stack ELK platform for Real-Time Monitoring of MCI DWBI Project.

**DW/BI Engineer** 1-Year

Jan. 2019 - Dec. 2019

- Working with Oracle RDBMS and Tools like: ODI OBIEE Oracle Cloud
- Built and deployed ETL packages, focusing on high-availability, Fault Tolerance, and Auto-Scaling.
- Developed **KPI Dashboards** to control system and product health.
- Development of **Telecom Interconnect** analysis area from scratch to **FACT & DIM** level

**Software Developer** 

MCI TELECOMMUNICATIONS

1-Year

Sep. 2015 - Sep. 2016

BRTel(Blue-Ray Telecommunications)

- Work with Rabbit-MQ and MySQL for fast and reliable message passing.
- implementation pf Value-Added Services based on SMS.
- Develop **Android** and **IOS** application for fan-service of Iranian soccer teams.
- Worked in a **Agile** team with **JIRA** management.

SOFTWARE

#### PhD. Candidate in Electrical Engineering

KAIST

ARTIFICIAL INTELLIGENCE Sep. 2020 - Exp. Jul. 2025

• Advisor: Prof. JeaKyun Moon

#### **B.Sc. in Computer Engineering**

Amirkabir University of Technology

Sep. 2017 - Exp. Jul. 2020

• Advisor: Prof. Mohammad Mahdi Ebadzadeh

- Thesis Title: Multi-Agent Deep Reinforcement Learning on Soccer Robot
- **Description:** The goal of this project is to accomplish a simple task of a soccer match by using **DeepRL** on a **multi-agent robots**, to reach this goal; I implemented a 3D soccer simulator, a distributed multi-agent software architecture and a MARL method on the ROS framework.

#### **B.Sc.** in Electrical Engineering

Amirkabir University of Technology

TELECOMMUNICATION Mar. 2015 - Exp. Jul. 2017

- Advisor: Prof. MohammadAzam Khosravi
- Entering Top Technical University of Iran without taking national exam when I was 16 as a Talented Student.
- Withdrawal at the end of the second year to focus on Software Engineering

### Program Committees \_\_\_\_\_

2019	Advisory Board, Al WorldCup	S. Korea, KAIST
2019	League Co-Chair, Fira RoboWorld Cup	S. Korea, Changwon
2019	League Chair, FIRACup IranOpen	Iran, AUT
2018	Technical Committee, Fira RoboWorld Cup	Taiwan, NTNU
2018	Technical Committee, Al WorldCup	S. Korea, KAIST
2018	Technical Committee, Robocup IranOpen	Iran, QAIU
2018	Technical Committee, FIRACup IranOpen	Iran, AUT
2017	Technical Committee, FIRACup IranOpen	Iran, AUT
2017	Organization Committee, Robocup IranOpen	Iran, QAIU
2016	Organization Committee, FIRACup IranOpen	Iran, AUT

### **Honors & Awards**.

#### INTERNATIONAL

2019	EurAl Full-Travel Grant, The 2019 ACAI Summer School: AI for Multi-Agent Worlds	Chania, Greece
2018	Finalist, Top 14 Among 3,224 Teams, Alibaba (Tianchi) BigData Competition: Zero Shot Image Recognition	China
2018	Finalist, Top 40 Among 780 Teams, Russian Al Challenge: Code Ball (3D multi-agent soccer simulation)	Russia
2018	<b>3rd Place</b> , FIRA Robo World Cup: 2D Soccer Simulation	Taichung, Taiwan
2018	<b>3rd Place</b> , FIRA Robo World Cup: Robot Challenge Simulation	Taichung, Taiwan
2017	4th Place, RoboCup: Small Size League	Nagoya, Japan
2016	<b>6th Place</b> , RoboCup: Small Size League	Leipzig, Germany
2015	8th Place, RoboCup: Small Size League	Hefei, China
2014	1st Place, RoboCup: Junior Soccer League	Joao Pessoa, Brasil
2014	Spirit of RoboCup Award, RoboCup: Junior Soccer League	Joao Pessoa, Brasil
2014	Best Poster and Presentation Award, RoboCup: Junior Soccer League	Joao Pessoa, Brasil

#### **DOMESTIC**

2017	Technical Challenge Championship, IranOpen RoboCup: Small Size League	Tehran, Iran
2017	<b>3rd Place</b> , IranOpen RoboCup: Small Size League	Tehran, Iran
2017	4th Place Among 964 Teams, Sharif AI Challenge 2017	Tehran, Iran
2016	1st Place, IranOpen Fira RoboWorldCup: Soccer Robots (Mirosot)	Tehran, Iran
2016	2nd Place, Amirkabir AI Competition : Othello Player	Tehran, Iran
2014	2nd Round Qualified, The Iranian Mathematical Olympiad	Tehran, Iran
2014	2nd Round Qualified, The Iranian Informatics Olympiad	Tehran, Iran

#### **ROS-based Architecture for Multi-agent Soccer Robots**

FIRA World Cup and Summit

RoboCup Competitions

FIRA ROBOWORLDCUP AND CONGRESS 2019

• Extended Abstract: Multi-Agent Architecture for Soccer Robots based on ROS, M.M. Rahimi et al. Link • 3-Min Oral Presentation, M.M. Rahimi Link

#### Parsian Extended Team Description Paper THE ANNUAL ROBOCUP INTERNATIONAL SYMPOSIUM

• PARSIAN 2019 Extended Team Description Paper, K. Behzad et al.

- PARSIAN 2018 Extended Team Description Paper, M.M. Rahimi et al. Link
- PARSIAN 2017 Extended Team Description Paper, M.M. Rahimi et al. Link
- PARSIAN 2016 Extended Team Description Paper, M.M. Rahimi et al. Link
- PARSIAN 2015 Extended Team Description Paper, A. Zolanvari et al. Link

#### **OPEM: Open Source PEM Cell Simulation Tool**

JOSS

2015 - 2019

THE JOURNAL OF OPEN SOURCE SOFTWARE

- Report about Implementation and Usage of the OPEM package.
- Published On The Journal of Open Source Software. Link

#### **QPage: Free Project For Creating Academic Homepage Without Any Code**

Zenodo

2017

**DEVELOPER AND AUTHOR** 

- Report about Implementation and Usage of the QPage package.
- · Published On Zenodo . Link

### **Teaching**

#### **Artificial Intelligence - TA**

Fall 2019

CE DEPARTMENT @ AMIRKABIR UNIVERSITY OF TECHNOLOGY

Prof. Ahmad Nickabadi

- Teaching Evolutionary Search and Optimization Algorithm
- Prepare the Final Project and Grading of home-works

#### Artificial Intelligence - TA

Fall 2018

CE DEPARTMENT @ AMIRKABIR UNIVERSITY OF TECHNOLOGY

Prof. Ahmad Nickabadi

• Grading of home-works

#### **Advance Programming - TA**

Fall 2018

EE DEPARTMENT @ AMIRKABIR UNIVERSITY OF TECHNOLOGY

Prof. Amir Jahanshahi

- Teaching Bash, Git, Web Front-End and Databases as side workshops
- · Grade Home-works and review solutions in Class.

#### **Basic Programming - TA**

Fall 2017

EE DEPARTMENT @ AMIRKABIR UNIVERSITY OF TECHNOLOGY

Prof Amir Jahanshahi

- Teaching C and C++
- · Review solutions of home-works in class

#### **Robotic Summer School - Workshop Instructor**

2015 - 2018

CE @ AMIRKABIR UNIVERSITY OF TECHNOLOGY

**Programming Languages** 

Prof. Soursh SadeghNejad

- Being the Teacher of the event for four continuous year.
- Teaching Linux, Git, C++, Python, Qt Frameworks, ROS Framework and Gazebo in Basic and Advance level in eighteen 6-hour sessions.

### Skills

• System: C/C++(10 Years), Bash/Zsh(5 Years), Python(5 Years), JAVA(4 Years), Rust(2 Years)

Web: JavaScript(6 Years), NodeJS(2 Years), HTML/CSS(6 Years)

• Functional: Lisp(1 Year), Racket(1 Year)

Hardware: VHDL(3 Years), Verilog(1 Year)

**Frameworks** Qt(6 Years), ROS(3 Years), OpenCV(3 Years), Pytorch(2 Year), Tensorflow(1 Years), OpenAI GYM(1 Year)

Simulations Platform Gazebo(3 Year), Webots(2 Years), Mujoco(1 Year), V-Rep(1 Year)

**Version Control** Git(6 Years), Subversion(3 Years)

**Continuous Integration** Gitlab CI/CD(6 Years), Travis(4 Years), Circle CI(2 Years), Github Workflow(1 Year)

**Operating Systems** MacOs(8 Years), Ubuntu(6 Years), Redhat(2 Years), SunOs(1 Year)

**BigData Stack** Hadoop Ecosystem(1 Year), ELK Stack(1 Year), Kafka(1 Year), Spark(1 Year)

**Databases** Oracle(2 Years), Postgres(1 Year), MySql(1 Year), Sqllite(6 Years) Languages Persian(native), English(10 Years), Arabic(4 Years), Korean(1 Year)

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### **Open-Source Contribution**

#### **GENERAL**

#### **OH-MY-ZSH – Community-Driven Framework for Managing your ZSH Configuration.**

Contributer

ROBBYRUSSELL/OH-MY-ZSH

- · Add Spotify CLI support.
- Improve MacOs features

#### **PYCM - Multi-class Confusion Matrix Library in Python**

Contributer

SEPANDHAGHIGHI/PYCM

- · Fine-tune Models and fix bug.
- · Add OSX Support.
- · Add test and CI on Travis.

#### QPAGE - Free Project For Creating Academic Homepage Without Any Code In 3min

Co-Owner

SEPANDHAGHIGHI/QPAGE

- · Implementation of styles and templates.
- Add UNIX/MacOs Support.

#### **OPEM - Open Source PEM Fuel Cell Simulation Tool**

Co-Owner

ECSIM/OPEM

- · MacOs Support and maintenance.
- Implement Static Simulation Analysis.
- Implement Test and CI on Travis.

#### **GOPEM - GUI for OPEM Simulation**

Creator

ECSIM/GOPEM

- Written in Python by pyQt and matplotlib
- · Implement test and CI on Travis.
- Easy Install package deployed by PyInstaller.

#### Spotify-AdBlocker - Listen to Spotify - W/O Ads!

Creator

MAH197/SPOTIFY-ADBLOCKER

- Written with AppleScript
- Mute, Replace and Remove ads from Spotify.

#### SpotifyControl - Search and Play Music from Spotify in Terminal

Creator

MAH197/SPOTIFYCONTROL

- Written with AppleScript
- Manage all Spotify functionality including search.

#### ROBOCUP & FIRACUP

#### GrSim - RoboCup Small Size Robot Soccer Simulator

Maintainer

ROBOCUP-SSL/GRSIM

- · Add OSX Support.
- Implement test and CI on Travis.
- Improve performance, fix bugs and add new rules and requirements.

#### FIRASim - FiraCup 2D Soccer Simulation Platform

Maintainer

FIRA-SIMUROSOT/FIRASIM

- · Implementation of Robot models.
- Add Win/Linux/OSX Support.
- Implement test and CI on Travis.
- Improve performance, fix bugs and add new rules and requirements.

#### SimPlus - The RoboCup Rescue Simulation environment for Robocup Junior Rescue

Contributer

ROBOCUP-SIMPLUS/SIMPLUS-VREP

- · Implementation of communication messages.
- Implementation of game server.
- Implementation of python client.
- Implementation of GRPC async protocol.

#### SSL-VISION - Shared Vision System For The RoboCup Small Size League

Contributer

ROBOCUP-SSL/SSL-VISION

- Add OSX Support.
- · Implementation of new rules and requirements.

### **Remarkable Projects**

#### XQMIX - Extended QMix for playing Multi Agent Starcraft II Challenge (SMAC)

MAH197/XQMIX

- Implementation in Pytorch
- Extend the original Qmix by Noisy Nets and Multi-Step Training

#### XMANN – External Memory and Neural Networks

MAH197/XMANN

- Implementation in Pytorch in a fully Modular setting
- Robust Implementation of NTM, DNC, and MANN architecture.
- · All benchmark tasks applied and tested.

#### **SUMO - Reinforcement Learning on Crossroad Traffic Lights.**

MAH197/SUMO

- Implementation in Pytorch
- Implemented both **DQN** and **DDPG** for discete and continous cases

## SSL Visual Planner – A User Friendly software to arrange plans for Multi-Agent Soccer Robots

PARSIANROBOTICLAB/SSL-VISUAL-PLANNER

- · Add OSX Support.
- Implementation in C++ and Qt

#### SSL FEdit – Formation Editor For Multi-Agent Soccer Robots

PARSIANROBOTICLAB/SSL-FEDIT

- Migrated from RoboCup Soccer Simulation 2D
- Implemented in C++ and Qt.

#### RAIC2019 - RussianAlCup, Soccer Platform using Long Term Prediction

PARSIANROBOTICLAB/RAIC2019

- · Implemented in Rust
- Prediction of Ball and Agents in 3D Soccer Environment
- · Multi-agent AI with Cooperation for Pass and Receive

#### Simurosot-Middle - Simurosot Base Code MiroSot

PARSIANROBOTICLAB/SIMUROSOT-MIDDLE

- Implemented in C++ and VisualStudio.
- Strong debug tools with network tools.

#### **ZeroShot Learning for ZJU AI Competition (GAN Approach)**

PARSIANROBOTICLAB/ZERO-SHOT-LEARNING

- · GAN approach implementation
- Manifold implementation for classification

#### ImageSegmentation - Image Segmentation by Hidden Markov Models

MAHI97/IMAGESEGMENTATION

- Written in Python / Jupyter Notebook
- Implement Naive Bayes and HMM for pixel labeling.
- Improve quality of segmentation by simulated annealing.

#### PersianNews-Retrieval - All sort of Retrieval Process on already fetched Persian News

MAH197/PERSIANNEWS-RETRIEVAL

- Written in Python / Jupyter Notebook
- Implement normalization, stemming, tokenizer and detect stop-words
- Improve quality search by invert indexing and tf-idf rankings

#### ClassicSearch - Implementation of Classic Search Algorithms for some Classic Problems

MAHI97/CLASSICSEARCH

- Written in C++
- Implement Bidirectional, BFS, A\*, DFS and UCS Searches.
- Model and Solve 2D Navigation, Puzzle 15 and Water Buckets Problems.

#### Non-Classic-Search - Beyond Search Algorithems

MAH197/NON-CLASSIC-SEARCH

- Written in Python
- Implement All sort of Hill Climbing, Genetic and Simulated Annealing
- Model and Solve 8 Queen, Math Equations and Graph Partitioning Problems.

Game Theory and MARL course

Prof. Jinkyoo Park

Moon Lab.

Prof. JeaKyun Moon

Game Theory and MARL course

Prof. Jinkyoo Park

Parsian Robotic Lab.

Prof. Mohammad Azam Khosravi

PGM Course

Prof. Ahmand Nikabadi

Information Retrieval course.

Prof. Ahmand Nikabadi

Artificial Intelligence Course.

Prof. Ahmand Nikabadi

Artificial Intelligence Course.

Prof. Ahmand Nikabadi

#### OthelloPlayer - AI & Learning for Othello Game

MAHI97/OTHELLOPLAYER

- · Written in Java
- Implement All MinMax Tree with alpha-beta pruning.
- Implementation of Opening Book and Ending Scenarios.
- Implementation of Genetic Optimizer to find weight through self-playing.

#### InvertSearch - Positional Index and searching on Huge text data files with B-Trees

MAH197/INVERTSEARCH

- Written in C++ and Qt
- All data structures like List and Vector implemented from Scratch.
- · Using Balance trees for indexing and search.
- · Multi-thread Processing.

#### FSM - Finite-State Machine, Automata, and Graph Computing

MAHI97/FSM

- Written in C++ and Qt
- · Solve FSM language with backtracking.
- · Remove Loop and improve the FSM.

#### Persian-Compiler - Just Another Persian Compiler

MAHI97/PERSIAN-COMPILER

- Written in pure C with help of Yacc and Flex
- Support Recursive function, array and pointers

#### NUMEX-Lang – The Pure Functional Interpreter for Pure Functional Language

MAH197/NUMEX-LANG

• Written in **Racket** (a functional PL driven from Lisp)

#### LSTM\_FPGA - Implementation of LSTM in FPGA with VHDL

MAH197/LSTM\_FPGA

- Written in VHDL
- Deployed of the Xillinx Spartan 3 FPGA Hardware
- Train and Test for simple **Translation** from Greek to English

#### SAYEH - Basic Computer (Simple Architecture Yet Enough Hardware!)

MAH197/SAYEH

- · Written in VHDL
- Implementation of Memory and 16-bit CPU (ALU, Controller and Data Path)
- · Implementation of Pipeline with Branch Prediction.
- Implementation of Cache with multiple strategy for SAYEH.

#### C-Compiler – A Compiler to Generate SAYEH Assembly Instruction from C Source Code

MAHI97/C-COMPILER

- Written in C++
- Implementation of Lexical and Syntax Analysis
- Implementation of Assembler.

#### USART\_GUI - GUI Application that connect to any device for Read and Write via USART

MAH197/USART\_GUI

- Written in C++ and Ot
- Support every OS and Platform for execution
- Support all sort of device that use USART with any Frequency

#### MircroProject - Receiving Morse Code from PC and Translate to Beep with any Frequency

Micro-Controller Course.

MAHI97/MIRCROPROJECT

· Design Electronic PCB with Altium Designer

- Assemble and Program the PCB
- · Direct Connect to PC with USART

#### P2PFileTransfer - (Torrent) Sending File Peer-to-Peer over from multiple source and receiver

MAHI97/P2PFILETRANSFER

Written in JAVA

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• Distributed file transfer from multiple source to multiple destination

Data Structure Course.

Prof. Ahmand Nikabadi

Prof. Mahdi Dehghan Takhtefoladi

Artificial Intelligence Course.

Data Structure Course

Prof. Mahdi Dehghan Takhtefoladi

Compiler Course.

Prof. Mohammad Reza Razzazi

Programming Languages Course.

Prof. Mehran Soleyman Fallah

FPGA Course.

Prof. Morteza Saheb Zamani

Computer Architecture Course.

Prof. Saeed Shiry Gheydari

Computer Architecture Course.

Prof. Saeed Shiry Gheydari

Micro-Controller Course. Prof. Mohammad Mahdi Homayounpour

Prof. Mohammad Mahdi Homayounpour

Network Course

Prof. Masoud Sabaei

Prof. Masoud Sabaei

- MAHI97/CALCNET
- Written in **JAVA**
- Use Master-Slave Architecture for task handling.